

## 6.5Gbps 4-Lane SAS2/SATA/XAUI ReDriver™ with Equalization, Emphasis and Flow-through pinout

### Features

- Up to 6.5Gbps SAS2/SATA/XAUI ReDriver
- Supporting 8 differential channels or 4 ports
- I<sup>2</sup>C configuration controls (3.3V Tolerant)
- Adjustable receiver equalization
- Adjustable transmitter amplitude and emphasis
- 50-Ohm input/output termination
- Mux/Demux feature
- Channel loop-back
- OOB fully supported
- Single supply voltage, 1.2V ± 0.05V
- Power down modes
- Packaging: 56-contact TQFN (5mm x 11mm)

### Description

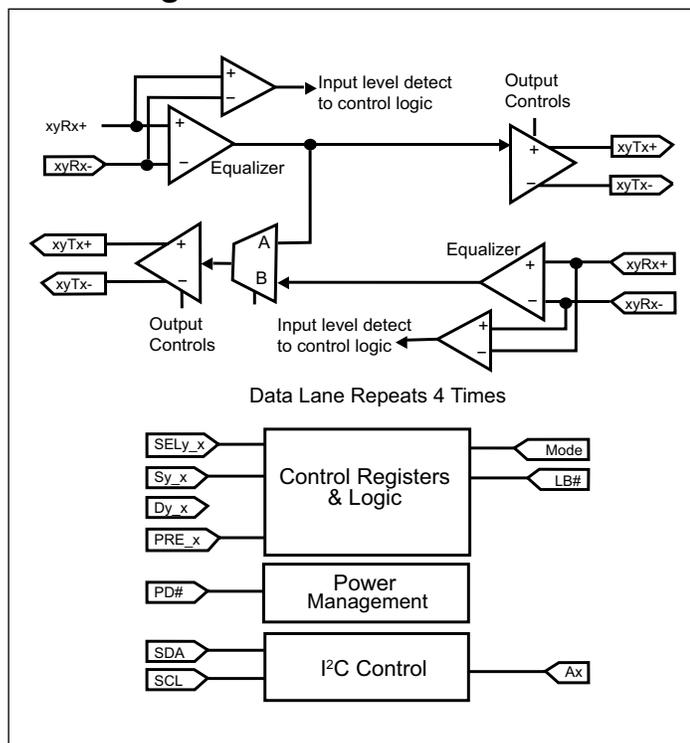
Pericom Semiconductor's PI2EQX6874 is a low power, SAS, SATA, XAUI signal ReDriver. The device provides programmable equalization, amplification, and emphasis by using 8 select bits, to optimize performance over a variety of physical mediums by reducing Inter-symbol interference.

PI2EQX6874 supports eight 100-Ohm Differential CML data I/O's between the Protocol ASIC to a switch fabric, across a backplane, or extends the signals across other distant data pathways on the user's platform.

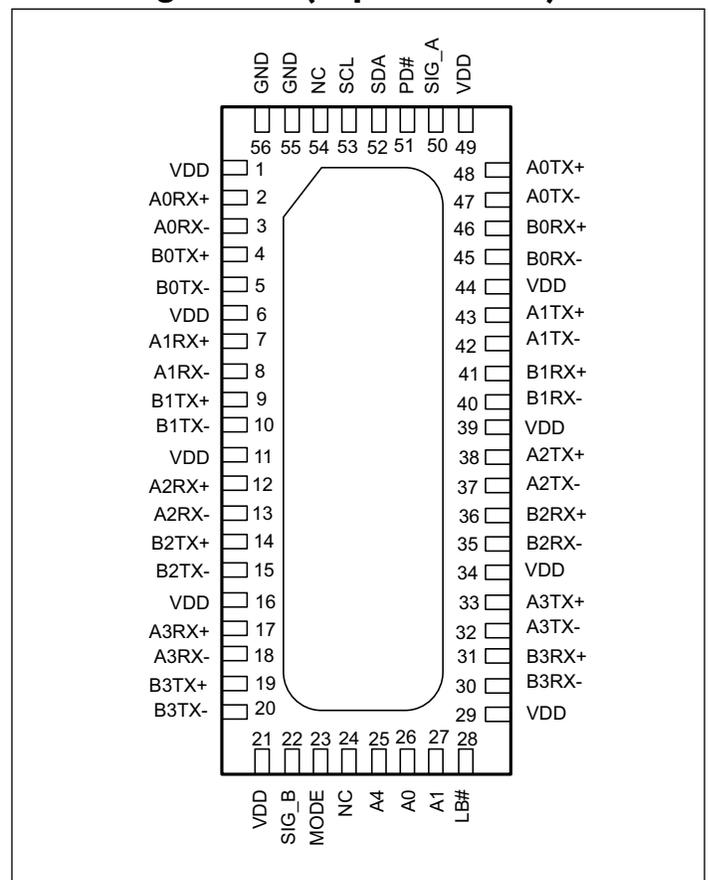
The integrated equalization circuitry provides flexibility with signal integrity of the signal before the ReDriver, whereas the integrated emphasis circuitry provides flexibility with signal integrity of the signal after the ReDriver.

In addition to providing signal re-conditioning, Pericom's PI2EQX6874 also provides power management Stand-by mode controlled via I<sup>2</sup>C register.

### Block Diagram



### Pin Configuration (Top-Side View)



**Pin Description**

Pin #	Pin Name	Type	Description
<b>Data Signals</b>			
2 3	A0RX+, A0RX-	I I	CML inputs for Channel A0, with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
48 47	A0TX+, A0TX-	O O	CML outputs for Channel A0, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
7 8	A1RX+, A1RX-	I I	CML inputs for Channel A1, with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
43 42	A1TX+, A1TX-	O O	CML outputs for Channel A1, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
12 13	A2RX+, A2RX-	I I	CML inputs for Channel A2, with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
38 37	A2TX+, A2TX-	O O	CML outputs for Channel A2, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
17 18	A3RX+, A3RX-	I I	CML inputs for Channel A3 with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
33 32	A3TX+, A3TX-	O O	CML outputs for Channel A3, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
46 45	B0RX+, B0RX-	I I	CML inputs for Channel B0, with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
4 5	B0TX+, B0TX-	O O	CML outputs for Channel B0, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
41 40	B1RX+, B1RX-	I I	CML inputs for Channel B1, with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
9 10	B1TX+, B1TX-	O O	CML outputs for Channel B1, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
36 35	B2RX+, B2RX-	I I	CML inputs for Channel B2, with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
14 15	B2TX+, B2TX-	O O	CML outputs for Channel B2, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
31 30	B3RX+, B3RX-	I I	CML inputs for Channel B3, with internal 50-Ohm pull-down. Goes to high-impedance during power-down (PD#=0).
19 20	B3TX+, B3TX-	O O	CML outputs for Channel B3, with internal 50-Ohm pull-up. Goes to high-impedance during power-down (PD#=0).
<b>Control Signals</b>			
26, 27, 25	A0, A1, A4	I	I <sup>2</sup> C programmable address bit A0, A1 and A4.
28	LB#	I	Input with internal 100K-Ohm pull-up resistor. LB# = High or open for normal operation. LB# = Low for loopback connection of A_RX to A_TX and B_TX.
22	SIG_B	0	Signal detect output for channel B. SIG_B indicates a valid input signal which is > Vth at the differential inputs. With 100K-Ohm internal pull up.
23	MODE	I	A LVCMOS high level disables I <sup>2</sup> C operation. With 100K-Ohm internal pull up.
24, 54	NC		Do Not Connect (Reserved for future use.)
50	SIG_A	0	Signal detect output for channel A. SIG_A indicates a valid input signal which is > Vth at the differential inputs. With 100K-Ohm pull up.

**(Continued)**

Pin #	Pin Name	Type	Description
51	PD#	I	Input with internal 100K-Ohm pull-up resistor, PD# =High or open is normal operation, PD# =Low disable the IC, and set IC to power down mode, both input and output go Hi-Z.
52	SDA	I/O	I <sup>2</sup> C SDA data input. Up to 3.3V input tolerance
53	SCL	I/O	I <sup>2</sup> C SCL clock input. Up to 3.3V input tolerance.
<b>Power Pins</b>			
55, 56, Center Pad	GND	PWR	Supply Ground
1, 6, 11, 16, 21, 29, 34, 39, 44, 49	VDD	PWR	1.2V Supply Voltage ± 0.05V

## DESCRIPTION of OPERATION

### Configuration Modes

Device configuration can be performed in two ways depending on the state of the MODE input. MODE determines whether IC configuration is from the input pins or via I<sup>2</sup>C control. Note that the MODE pin is not latched, and is always active to enable or disable I<sup>2</sup>C access. When MODE is set high, the configuration input pins determine the configuration operating state and changes to the input configuration pins will change the operating mode.

When the MODE pin is low, programming of all control registers via I<sup>2</sup>C is allowed. During initial power-on, the value at the configuration input pins: LB#, PD#, DE\_A, DE\_B, SEL0\_A, SEL1\_A, SEL2\_A, D0\_A, D1\_A, D2\_A, S0\_A, S1\_A, SEL0\_B, SEL1\_B, SEL2\_B, D0\_B, D1\_B, D2\_B, S0\_B, S1\_B, will be latched to the configuration registers as initial startup states.

### Equalizer Configuration

The PI2EQX6874 input equalizer compensates for signal attenuation and Inter-Symbol Interference (ISI) resulting from long signal traces or cables, vias, signal crosstalk and other factors, by boosting the gain of high-frequency signal components. Because either too little, or too much, signal compensation may be non-optimal eight levels are provided to adjust for any application.

Equalizer configuration is performed in two ways determined by the state of the MODE pin. When the device first powers up, the SELx\_[A:B] input pins are read into the appropriate control registers to set the equalization characteristic. If the MODE pin is low, reprogramming of these control registers via I<sup>2</sup>C is allowed.

Each group of four channels, A and B, has separate equalization control, and all four channels within the group are assigned the same configuration state. The Equalizer Selection table below describes pin strapping options and associated operation of the equalizer. Refer to the section on I<sup>2</sup>C programming for information on software configuration of the equalizer.

### Equalizer Selection

SEL2_[A:B]	SEL1_[A:B]	SEL0_[A:B]	@1.5GHz	@3.0GHz
0	0	0	0.8dB	1.5dB
0	0	1	1.0dB	1.9dB
0	1	0	1.5dB	3.2dB
0	1	1	2.5dB	5.2dB
1	0	0	3.5dB	6.9dB
1	0	1	4.4dB	8.3dB
1	1	0	5.9dB	10.4dB
1	1	1	8.7dB	13.8dB

## Output Configuration

The PI2EQX6874 provides flexible output strength and emphasis controls to provide the optimum signal to pre-compensate for losses across long trace or noisy environments so that the receiver gets a clean with good eye opening. Control of output configuration is grouped for the A and B channels, so that each channel within the group has the same setting.

Output configuration is performed in two ways depending on the state of the MODE pin. When the device first powers up, the Sx\_[A:B], and Dx\_[A:B] input pins are read into the appropriate control registers to set the power-on state. If the MODE pin is low, reprogramming of these control registers via I<sup>2</sup>C is allowed.

The Output Swing Control table shows available configuration settings for output level control, as specified using the Sx\_y pins and registers. Output swing settings are independent of the data rate.

### Output Swing Control

S1_[A:B]	S0_[A:B]	Swing (Differential)
0	0	1.1V
0	1	0.5V
1	0	0.8V
1	1	1.0V

Emphasis settings are determined by the state of the DEx\_y input pins and configuration registers, as shown in the Output Emphasis table below. Pre-emphasis is selected as the default power-on mode, but can be changed to de-emphasis via reprogramming the Loopback and Emphasis Control register using the I<sup>2</sup>C interface. Output emphasis settings are independent of the data rate.

### Output Emphasis Adjustment

D2_[A:B]	D1_[A:B]	Emphasis
0	0	0dB
0	1	3.5dB
1	0	5.5dB
1	1	7.5dB

## Input Level Detect

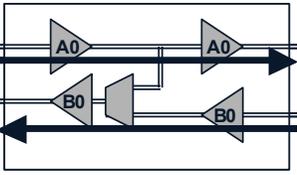
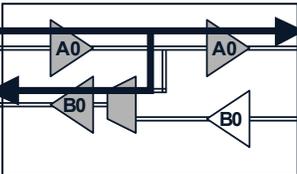
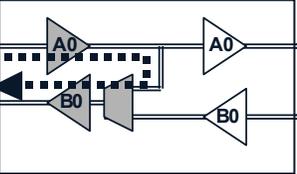
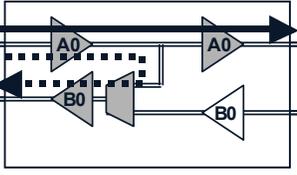
An input level detect and output squelch function is provided on each channel to eliminate re-transmission of input noise. A continuous signal level below the  $V_{th}$  threshold causes the output driver to drive both the plus and minus signal pair to the common mode voltage.

The input sensitivity can be adjusted via the input level threshold register for special requirements.

## Input Threshold Configuration

Bit	Threshold (mVppd)
7	180
6	160
5	140
4	120 (Default)
3	100
2	80
1	60
0	40

### Loopback Operation

Loopback Modes	CONDITIONS
 <p>NORMAL MODE A0Rx to A0Tx, B0Rx to B0Tx</p>	<p>LB_A0B0# = 1 INDIS_A0 = 0 OUTDIS_A0 = 0 INDIS_B0 = 0 OUTDIS_B0 = 0</p>
 <p>BROADCAST MODE A0Rx to A0Tx and B0Tx</p>	<p>LB_A0B0# = 0 INDIS_A0 = 0 OUTDIS_A0 = 0 INDIS_B0 = 1 OUTDIS_B0 = 0</p>
 <p>LOOPBACK MODE A0Rx to B0Tx</p>	<p>LB_A0B0# = 0 INDIS_A0 = 0 OUTDIS_A0 = 1 INDIS_B0 = 1 OUTDIS_B0 = 0</p>
 <p>DEMUX MODE Solid Line A0Rx to A0Tx</p> <p>DEMUX MODE Dashed Line A0Rx to B0Tx</p>	<p>LB_A0B0# = 1 INDIS_A0 = 0 OUTDIS_A0 = 0 INDIS_B0 = 1 OUTDIS_B0 = 1</p> <p>LB_A0B0# = 0 INDIS_A0 = 0 OUTDIS_A0 = 1 INDIS_B0 = 1 OUTDIS_B0 = 0</p>
	<p>MUX MODE Solid Line B0Rx to B0Tx</p> <p>MUX MODE Dashed Line A0Rx to B0Tx</p>

Each lane provides a loopback mode for test purposes which is controlled by a strapping pin and I<sup>2</sup>C register bit. The LB# pin controls all lanes together. When this pin is high normal data mode is enabled. When LB# is low the loopback feature is enabled. The adjacent figure diagrams this operation. Loopback is not intended to be dynamically switched, and the normal system application is to initialize to one configuration or the other.

The Loopback mode can also support mux/demux operation. Using I<sup>2</sup>C configuration, unused inputs and outputs can be disabled to minimize power and noise.

## I<sup>2</sup>C Operation

The integrated I<sup>2</sup>C interface operates as a slave device, supporting standard rate operation of 100Kbps, with 7-bit addressing mode. The data byte format is 8 bit bytes, and supports the format of indexing to be compatible with other bus devices. The index, or dummy byte will have no effect on the PI2EQX6874 operation. The bytes must be accessed in sequential order from the lowest to the highest byte with the ability to stop after any complete byte has been transferred. Address bits A4, A1 and A0 are programmable to support multiple chips environment. The Data is loaded until a Stop sequence is issued.

Note that the I<sup>2</sup>C inputs, SCL and SDA operate at 1.2V logic levels, and are 3.3V tolerant.

## Configuration Register Summary

Byte	Mnemonic	Function
0	SIG	Signal Detect, indicates valid input signal level
1	RSVD	Reserved for future use
2	LBEC	Loopback and Emphasis Control, provides for control of the loopback function and emphasis mode (pre-emphasis or de-emphasis)
3	INDIS	Channel Input Disable, controls whether s channels input buffer is enabled or disabled
4	OUTDIS	Channel Output Disable, controls whether a channel output buffer is enabled or disabled.
5	A0	Channel A0 configuration
6	B0	Channel B0 configuration
7	A1	Channel A1 configuration
8	B1	Channel B1 configuration
9	A2	Channel A2 configuration
10	B2	Channel B2 configuration
11	A3	Channel A3 configuration
12	B3	Channel B3 configuration
13	VTH	Input level threshold configuration
14	RSVD	Reserved for future use

## Register Description

### BYTE 0 - Signal Detect (SIG)

SIG<sub>xy</sub>=0=low input signal, SIG<sub>xy</sub>=1=valid input signal

Bit	7	6	5	4	3	2	1	0
<b>Name</b>	<b>SIG_A0</b>	<b>SIG_B0</b>	<b>SIG_A1</b>	<b>SIG_B1</b>	<b>SIG_A2</b>	<b>SIG_B2</b>	<b>SIG_A3</b>	<b>SIG_B3</b>
Type	R	R	R	R	R	R	R	R
Power-on State	X	X	X	X	X	X	X	X

Note: R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

The Signal Detect register provides information on the instantaneous status of the channel input from the Input Level Threshold Detect circuit. If the input level falls below the V<sub>th-</sub> level the relevant SIG<sub>xy</sub> bit will be 0, indicating a low-level noise or electrical idle input, resulting in the outputs going to the high-impedance off state or squelch mode. If the input level is above V<sub>th-</sub>, then SIG<sub>xy</sub> is 1, indicating a valid input signal, and active signal recovery operation.

### BYTE 1 - Reserved

Reserved Byte 1 is visible via the I<sup>2</sup>C interface. This is a read-only byte with an undefined initial state after power-up. This byte is reserved for future use.

### BYTE 2 - Loopback and Emphasis Control Register (LBEC)

LB<sub>xyxy</sub>#=0=loopback mode, LB<sub>xyxy</sub>#=1=normal mode,

Slumber = 1 = auto-power down slumber enabled,

Slumber = 0 = auto power down disabled

Bit	7	6	5	4	3	2	1	0
<b>Name</b>	<b>LB_A0B0#</b>	<b>LB_A1B1#</b>	<b>LB_A2B2#</b>	<b>LB_A3B3#</b>	<b>Slumber</b>	<b>Bypass</b>	<b>rsvd</b>	<b>rsvd</b>
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Power-on State	LB#	LB#	LB#	LB#	1	0	0	0

Note: R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

Individual control for each lane is provided for the loopback function via this register. Slumber mode, auto power down for all channels is enabled by slumber. Bypass is for IC manufacturing test only, and should always be set to "0" for normal operation.

### BYTE 3 - Channel Input Disable (INDIS)

INDIS<sub>xy</sub>=0=enable input, INDIS<sub>xy</sub>=1=disable input

Bit	7	6	5	4	3	2	1	0
<b>Name</b>	<b>INDIS_A0</b>	<b>INDIS_B0</b>	<b>INDIS_A1</b>	<b>INDIS_B1</b>	<b>INDIS_A2</b>	<b>INDIS_B2</b>	<b>INDIS_A3</b>	<b>INDIS_B3</b>
Type	R/W							
Power-on State	0	0	0	0	0	0	0	0

Note: R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

The Channel Input Disable register, provides control over the input buffer of each channel independently. When and INDIS<sub>xy</sub> bit is logic 1, then the input buffer is switched off and the input termination is high impedance. This feature can be used for PCB testing, and when only one input is used during Loopback as a demux function. When INDIS<sub>xy</sub> is at a logic 0 state then the input buffer is enabled (normal operating mode).

### BYTE 4 - Channel Output Disable (OUTDIS)

ODIS<sub>xy</sub>=0=enable output, ODIS<sub>xy</sub>=1=disable output

Bit	7	6	5	4	3	2	1	0
<b>Name</b>	<b>ODIS_A0</b>	<b>ODIS_B0</b>	<b>ODIS_A1</b>	<b>ODIS_B1</b>	<b>ODIS_A2</b>	<b>ODIS_B2</b>	<b>ODIS_A3</b>	<b>ODIS_B3</b>
Type	R/W							
Power-on State	0	0	0	0	0	0	0	0

Note: R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

The Channel Output Disable register, allows control over the output buffer of each channel independently. When and OUTDIS<sub>xy</sub> bit is logic 1, then the output buffer is switched off and the termination is high impedance. This feature can be used for PCB testing, and when only one output is used during Loopback as a mux function. When INDIS<sub>xy</sub> is at a logic 0 state then the input buffer is enabled (normal operating mode).

**BYTE 5 - A0 Channel Configuration**

**BYTE 6 - B0 Channel Configuration**

**BYTE 7 - A1 Channel Configuration**

**BYTE 8 - B1 Channel Configuration**

**BYTE 9 - A2 Channel Configuration**

**BYTE 10 - B2 Channel Configuration**

**BYTE 11 - A3 Channel Configuration**

**BYTE 12 - B3 Channel Configuration**

SELx\_B: Equalizer configuration (see Equalizer Configuration Table)

Dx\_B: Emphasis control (see Emphasis Configuration Table)

Sx\_B: Output level control (see Output Swing Configuration Table)

Bit	7	6	5	4	3	2	1	0
<b>Name</b>	<b>SEL0_XX</b>	<b>SEL1_XX</b>	<b>SEL2_XX</b>	<b>D0_XX</b>	<b>D1_XX</b>	<b>S0_XX</b>	<b>S1_XX</b>	<b>PD#</b>
Type	R/W	R/W	R/W	R/W	R/W	R/W	R/W	R/W
Power-on State	SEL0_XX	SEL1_XX	SEL2_XX	D0_XX	D1_XX	S0_XX	S1_XX	PD#

Note: R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

The Ax/Bx-Channel configuration registers are used to control the input equalizer and output emphasis, swing levels and power-down. These register bits are loaded from the input configuration pins of the same name at power-on. These bits may be changed if the PGM# input is set low to allow I<sup>2</sup>C configuration. Please refer to the tables (1) Equalizer Configuration, (2) Output Swing Configuration and (3) Output Emphasis Configuration earlier in this document for setting information.

**BYTE 13 - Input Level Threshold Configuration**

Bit	7	6	5	4	3	2	1	0
<b>Name</b>	<b>VTH7</b>	<b>VTH6</b>	<b>VTH5</b>	<b>VTH4</b>	<b>VTH3</b>	<b>VTH2</b>	<b>VTH1</b>	<b>VTH0</b>
Type	R/W							
Power-on State	1	1	1	0	1	1	1	1

Note:

R=Read only, W=Write only, R/W=Read and Write, X=Undefined, rsvd=reserved for future use

Only 1 bit can be enabled at a time

0 = enable level, 1 = disable level,

Refer to Input Threshold Table for configuration information.

**BYTE 14 - Reserved**

Reserved Byte 14 is visible via the I<sup>2</sup>C interface. This byte is R/W, is in an undefined state at power up, and should not be changed for normal operation.

## Transferring Data

Every byte put on the SDA line must be 8-bits long. Each byte has to be followed by an acknowledge bit. Data is transferred with the most significant bit (MSB) first (see the I<sup>2</sup>C Data Transfer diagram). The PI2EQX6874 will never hold the clock line SCL LOW to force the master into a wait state.

Note: Byte-write and byte-read transfers have a fixed offset of 0x00, because of the very small number of configuration bytes. An offset byte presented by a host to the PI2EQX6874 is not used.

## Addressing

Up to eight PI2EQX6874 devices can be connected to a single I<sup>2</sup>C bus. The PI2EQX6874 supports 7-bit addressing, with the LSB indicating either a read or write operation. The address for a specific device is determined by the A0, A1 and A4 input pins.

Address Assignment							
A6	A5	A4	A3	A2	A1	A0	R/W
1	1	Program	0	0	Programmable		1=R, 0=W

## Acknowledge

Data transfer with acknowledge is required from the master. When the master releases the SDA line (HIGH) during the acknowledge clock pulse, the PI2EQX6874 will pull down the SDA line during the acknowledge clock pulse so that it remains stable LOW during the HIGH period of this clock pulse as indicated in the I<sup>2</sup>C Data Transfer diagram. The PI2EQX6874 will generate an acknowledge after each byte has been received.

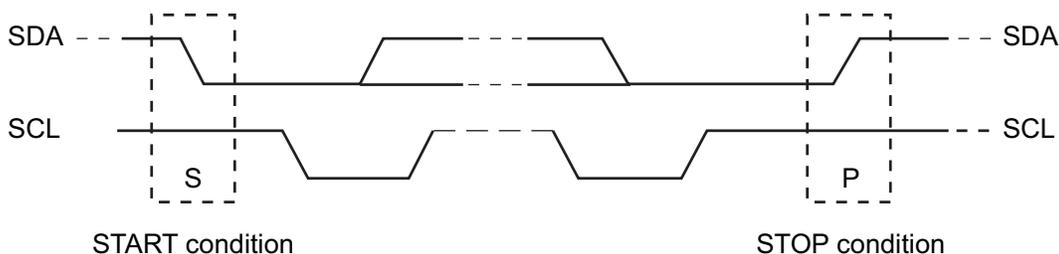
## Data Transfer

A data transfer cycle begins with the master issuing a start bit. After recognizing a start bit, the PI2EQX6874 will watch the next byte of information for a match with its address setting. When a match is found it will respond with a read or write of data on the following clocks. Each byte must be followed by an acknowledge bit, except for the last byte of a read cycle which ends with a stop bit. For a write cycle, the first data byte following the address byte is a dummy or fill byte that is not used by the PI2EQX6874. This byte is provided to provided compatibility with systems implementing 10-bit addressing. Data is transferred with the most significant bit (MSB) first.

## I<sup>2</sup>C Data Transfer

### Start & Stop Conditions

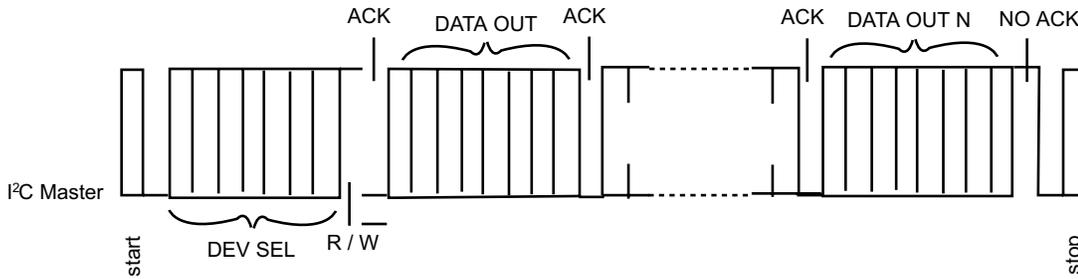
A HIGH to LOW transition on the SDA line while SCL is HIGH indicates a START condition. A LOW to HIGH transition on the SDA line while SCL is HIGH defines a STOP condition, as shown in the figure below.



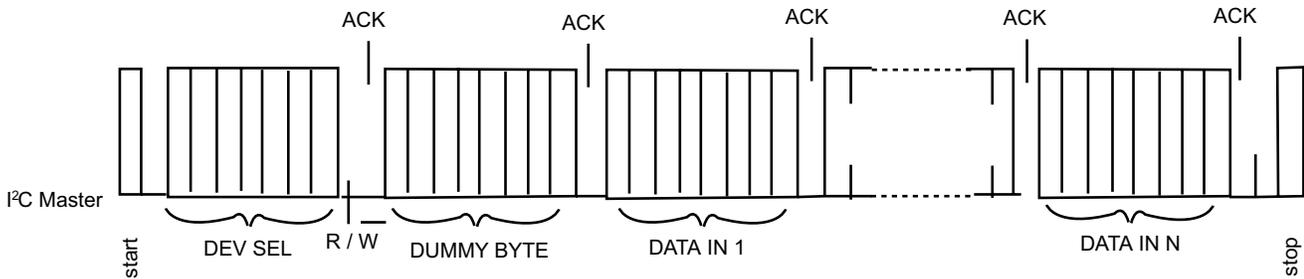
I<sup>2</sup>C START and STOP conditions.

## I<sup>2</sup>C Data Transfer

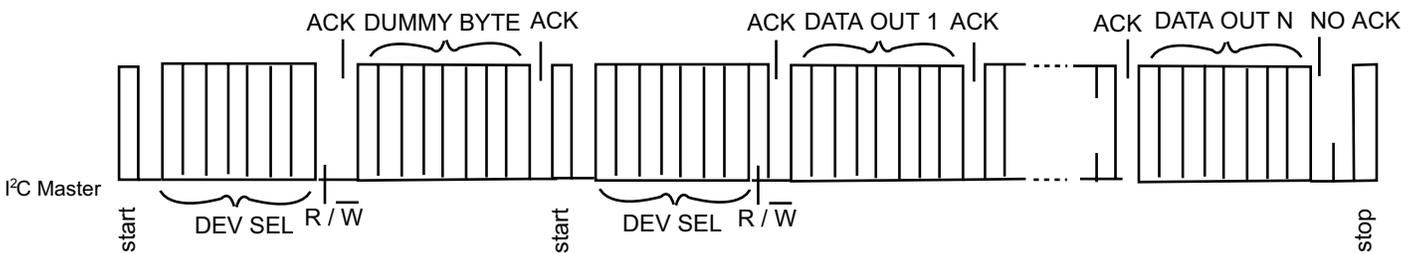
### 1. Read sequence



### 2. Write sequence



### 3. Combined sequence



**Notes:**

1. only block read and block write from the lowest byte are supported for this application.
2. for some I2C application, an offset address byte will be presented at the second byte in write command, which is called dummy byte here and will be simply ignored in this application for correct interoperation.

### Maximum Ratings

(Above which useful life may be impaired. For user guidelines, not tested.)

Storage Temperature . . . . .	-65°C to +150°C
Supply Voltage to Ground Potential . . . . .	-0.5V to +2.5V
DC SIG Voltage . . . . .	-0.5V to VDD +0.5V
Current Output . . . . .	-25mA to +25mA
Power Dissipation Continuous . . . . .	1W
Operating Temperature . . . . .	0 to +70°C
ESD, Human Body Model, SCL, SDA. . . . .	-1kV to +1kV
ESD, HBM, all other pins . . . . .	-2kV to +2kV

Note:

Stresses greater than those listed under MAXIMUM RATINGS may cause permanent damage to the device. This is a stress rating only and functional operation of the device at these or any other conditions above those indicated in the operational sections of this specification is not implied. Exposure to absolute maximum rating conditions for extended periods may affect reliability.

### AC/DC Electrical Characteristics

**Power Supply Characteristics (V<sub>DD</sub> = 1.2 ±0.05V, T<sub>A</sub> = 0 TO 70°C)**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
I <sub>DDactive</sub>	Power supply current - active	All channels switching @ 6.5 Gbps			800	mA
I <sub>DDstandby</sub>	Power supply current - standby	PD# = 0		1	5	
I <sub>DD-channel</sub>	Power supply current - per channel, Active			50		

**AC Performance Characteristics (V<sub>DD</sub> = 1.2 ±0.05V, T<sub>A</sub> = 0 TO 70°C)**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
T <sub>pd</sub>	Channel latency from input to output			750		ps

**CML Receiver Input ( $V_{DD} = 1.2 \pm 0.05V$ ,  $T_A = 0$  TO  $70^\circ C$ )**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
<b>CML Receiver Input</b>						
$Z_{RX-DC}$	DC Input Impedance		40			Ohm
$Z_{RX-DIFF-DC}$	DC Differential Input Impedance		85	100	115	
$V_{RX-DIFFP-P}$	Differential Input Peak-to-peak Voltage		240		1000	mV
$V_{RX-CM-ACP}$	AC Peak Common Mode Input Voltage				100	
$V_{TH-SD}$	OOB Signal detect input Threshold		75		200 <sup>(1)</sup>	mVppd
<b>Equalization</b>						
$T_J$	Total Jitter	Measured at 6Gbps/500			0.37	Ulp-p
$D_J$	Deterministic Jitter	Measured at 6Gbps/500			0.19	psrms

**Note:**

- Using Compliance test at 1.5Gbps and 3Gbps. Also using OOB (OOB is formed by ALIGNp primitive or D24.3) test patterns at 1.5Gbps. The ALIGN primitive (K28.5+D10.2+D27.3 = 0011111010+0101010101+0010011100). The D24.3 = 00110011001100110011

**CML Transmitter Output ( $V_{DD} = 1.2V \pm 0.05V$ ,  $T_A = 0$  to  $70^\circ C$ )**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
$Z_{TX-DIFF-DC}$	DC Differential TX Impedance		80	100	120	Ohms
$V_{TX-DIFFP-P0}$	Differential Peak-to-peak Output Voltage $V_{TX-DIFFP-P} = 2 *  V_{TX-D+} - V_{TX-D-} $	S[1:0] = 00, 0dB emphasis	0.9	1.1	1.3	V
		S[1:0] = 01, 0dB emphasis	0.3	0.5	0.7	
		S[1:0] = 10, 0dB emphasis	0.6	0.8	1	
		S[1:0] = 11, 0dB emphasis	0.8	1	1.2	
$V_{TX-C}$	Common-Mode Voltage $ V_{TX-D+} + V_{TX-D-}  / 2$			$V_{DD} - 0.6$		V
$t_F, t_R$	Transition Time	20% to 80%			150	ps
$t_F - t_R$	Mismatch Transition Time	@3Gbps			35	%
$V_{amp\_bal}$	TX amplitude imbalance	@3Gbps			10	
$T_{skew}$	TX differential skew				20	ps
$V_{cm\_ac}$	TX AC common mode voltage	@3Gbps			50	mVpp
$V_{cmOOB}$	OOB common mode delta voltage				50	mV
$V_{diffOOB}$	OOB differential delta voltage				25	

**Digital I/O DC Specifications ( $V_{DD} = 1.2V \pm 0.05V$ ,  $T_A = 0$  to  $70^\circ C$ )**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
$V_{IH}$	DC input logic high		$V_{DD}/2 + 0.2$		$V_{DD} + 0.3$	V
$V_{IL}$	DC input logic low		-0.3		$V_{DD}/2 - 0.2$	
$V_{OH}$	DC output logic high	$I_{OH} = 4mA$	$V_{DD} - 0.4$			
$V_{OL}$	DC output logic low	$I_{OL} = 4mA$			0.4	
$V_{hys}$	Hysteresis of Schmitt trigger input		0.1			
$I_{IH}^{(1)}$	Input high current				250	$\mu A$
$I_{IL1}^{(2)}$	Input low current		-250			
$I_{IL2}^{(3)}$	Input low current		-250			

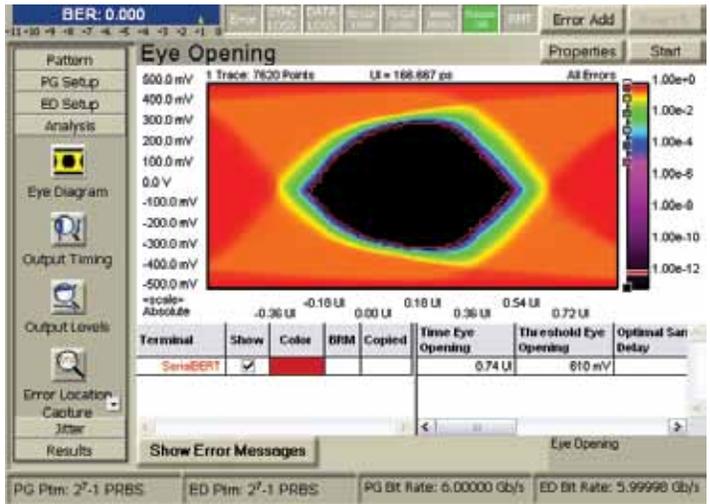
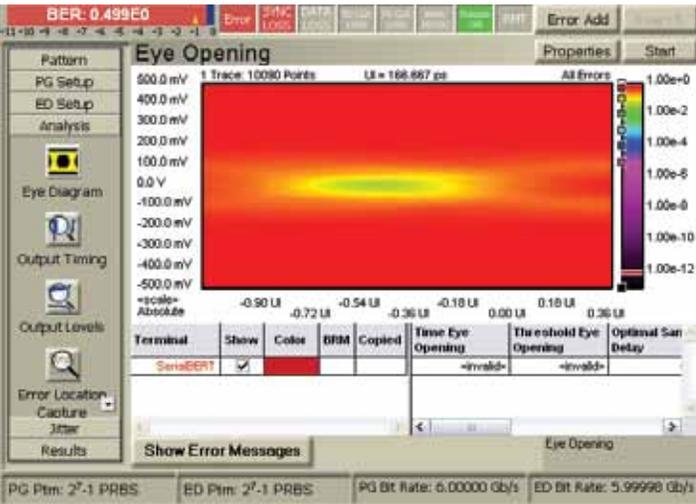
**Notes:**

1. Includes input signals A1, A2, A4, Dx\_[A:B], DE\_[A:B], LB#, MODE#, PD#, Sx\_[A:B], SCL, SDA, SEL\_x[A:B]
2. For control inputs without pullups: SCL, SDA
3. Control inputs with pull-ups include: Dx\_[A:B], DE\_[A:B], LB#, MODE#, PD#, Sx\_[A:B], SEL\_x[A:B], A1, A2, A4

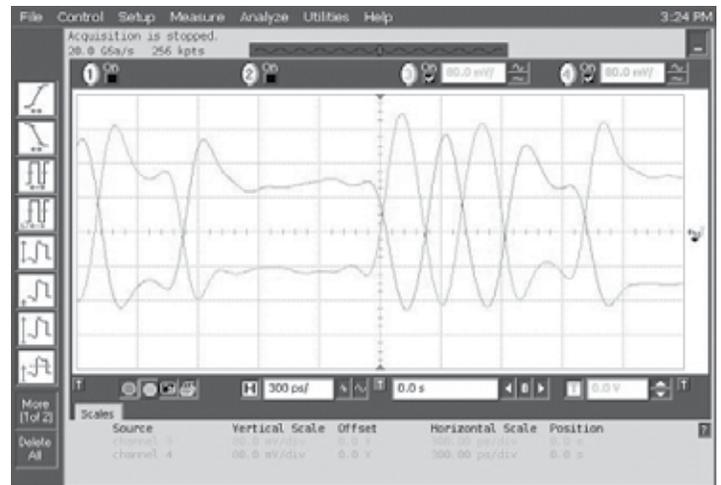
**SDA and SCL I/O for I<sup>2</sup>C-bus ( $V_{DD} = 1.2 \pm 0.05V$ ,  $T_A = 0$  to  $70^\circ C$ )**

Symbol	Parameter	Conditions	Min.	Typ.	Max.	Units
$V_{IH}$	DC input logic high		1.1		3.6	V
$V_{IL}$	DC input logic low		-0.3		0.7	
$V_{OL}$	DC output logic low	$I_{OL} = 3mA$			0.4	
$V_{hys}$	Hysteresis of Schmitt trigger input		0.2			

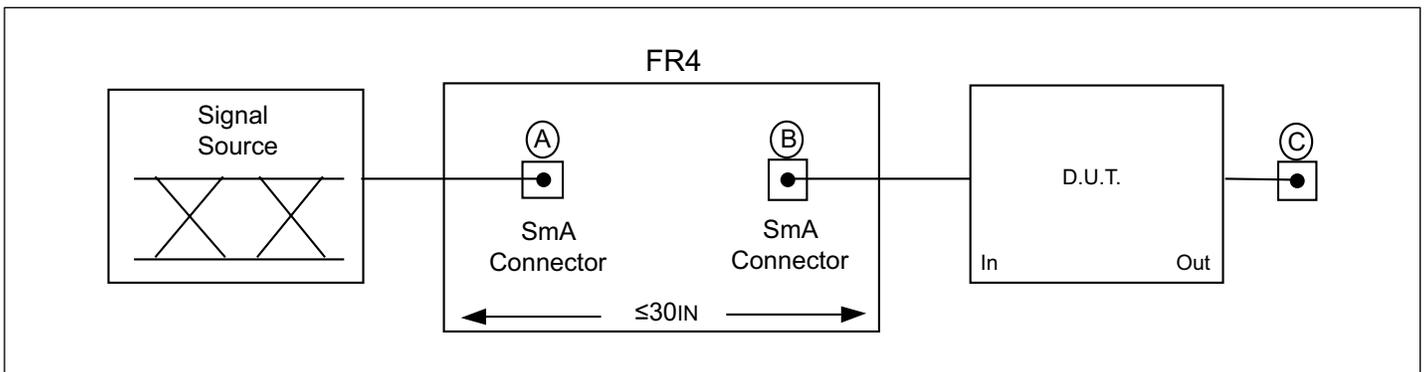




Signal Eyes at 13.8dB Input Equalization (EQ=111), 48” FR4 Input Trace and 36” Output Coax cable.

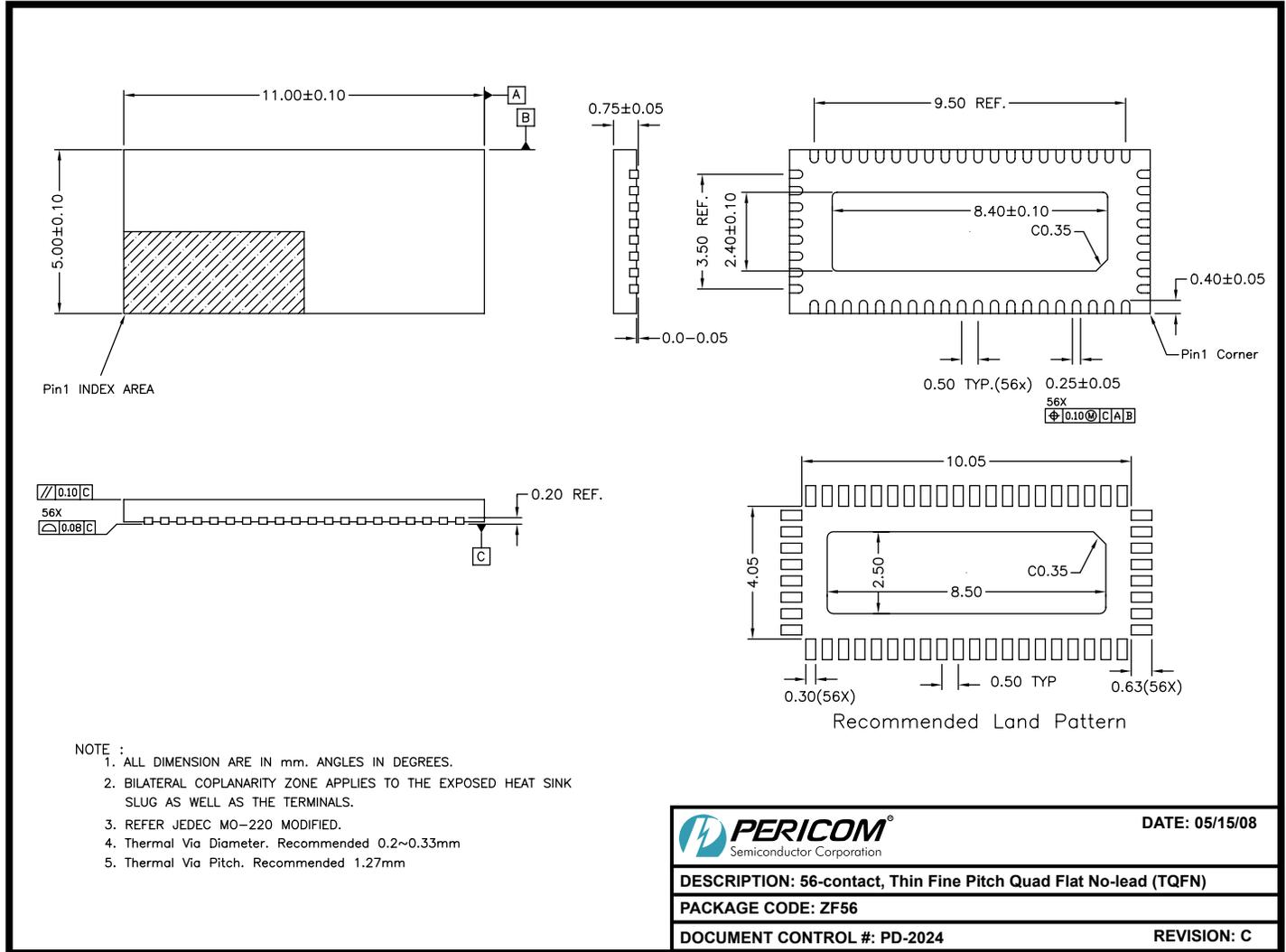


Data Waveforms, 3.0Gbps (left) & 6.0Gbps (right)



AC Test Circuit Referenced in the Electrical Characteristic Table

### Packaging Information



08-0208

Note: For latest package info, please check: <http://www.pericom.com/products/packaging/mechanicals.php>

### Ordering Information

Ordering Number	Package Code	Package Description
PI2EQX6874ZFE	ZF	Pb-free & Green 56-Contact TQFN

**Notes:**

- Thermal characteristics can be found on the company web site at [www.pericom.com/packaging/](http://www.pericom.com/packaging/)
- E = Pb-free and Green
- X suffix = Tape/Reel